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Accurate determination of an alkali-vapor–inert-gas diffusion coefficient using coherent transient emission from a density grating

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ABSTRACT

We demonstrate a technique for the accurate measurement of diffusion coefficients for alkali vapor in an inert buffer gas. The measurement was performed by establishing a spatially periodic density grating in isotopically pure ⁸⁷Rb vapor and observing the decaying coherent emission from the grating due to the diffusive motion of the vapor through N₂ buffer gas. We obtain a diffusion coefficient of $0.245 \pm 0.002 \text{ cm}^2/\text{s}$ at 50°C and 564 Torr. Scaling to atmospheric pressure, we obtain $D_0 = 0.1819 \pm 0.0024 \text{ cm}^2/\text{s}$. To the best of our knowledge, this represents the most accurate determination of the Rb-N₂ diffusion coefficient. Our measurements can be extended to different buffer gases and alkali vapors used for magnetometry and can be used to constrain theoretical diffusion models for these systems.

Keywords: Atomic coherences, Magnetometry, Diffusion, Coherent transient effects, Coherence gratings, Diode lasers

1. INTRODUCTION

We have relied on the successful development of a new class of low cost, homebuilt auto-locking laser systems (ALS)¹ to realize experiments in precision metrology that rely on the intrinsic sensitivity of atoms and the advantages of coherent transient techniques. ALS consist of vacuum-sealed, continuous wave (cw) diode lasers that can be frequency stabilized or scanned with respect to atomic, molecular, and temperature tunable frequency markers without human intervention using a digital controller that uses a variety of algorithms^{1,2}. This paper describes the most accurate measurement of a diffusion coefficient for an alkali atom in a nitrogen buffer gas environment, a measurement which plays a central role in the design of atomic magnetometers³.

1.1 Motivation

Spin-Exchange Relaxation–Free (SERF) atomic vapor magnetometers have leapfrogged superconducting sensors to become the most sensitive devices for measuring small magnetic fields and magnetic anomalies⁴. Such devices operate by optically pumping alkali vapor such as rubidium, into a specific internal state, thereby creating a macroscopic magnetic dipole moment that oscillates at the Larmor frequency, ω_L , associated with the external magnetic field. In a conventional time-domain magnetometer, ω_L is measured by observing the absorption of a weak probe laser⁵. SERF magnetometers achieve high precision by preserving the alignment of dipoles over extended time scales using high alkali densities and specific concentrations of buffer gases and quenching gases so that the optically pumped vapor diffuses slowly without decoherence due to radiation trapping and spin exchange collisions. Vapor cell magnetometers are used for the non-invasive exploration of metal and mineral deposits through large area aircraft borne surveys. Since these devices require large vapor densities and correspondingly high laser power (several Watts) for optical pumping, identifying the best configurations and realizing accurate measurements of diffusion coefficients to model magnetometer performance remain critical challenges. These coefficients are also necessary for understanding the dynamics of high-resolution biomedical imaging using spin-polarized noble gases⁶, testing collision models based on interatomic potentials⁷, and for monitoring the Earth's Ocean currents and interior dynamics using mesospheric sodium vapor magnetometery⁸.

2. METHODOLOGY

We have investigated a distinctive coherence magnetometer (CM) that can detect magnetic fields with potentially larger signal strengths than traditional magnetometers⁹⁻¹². CMs detect the evolution of atomic coherences that produce spatially periodic superpositions of atomic states. They produce coherent bursts containing Larmor oscillations along specific directions (due to phase matching) that can be detected over a larger dynamic range than probe transmission.

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Here, two laser pulses, overlapped at a small angle θ , create a transverse coherence grating (see Fig. 1). This angle defines the spacing between grating planes. When one of the pulses is turned on, the signal scattered from the grating along the other beam direction decays due to the diffusion of atoms between the planes.

In this work, we have exploited the long-lived decay of a magnetic field insensitive density grating that has the same spatial period as the coherence grating¹³. By measuring the decay time and its characteristic $1/\theta^2$ dependence in isotopically pure ⁸⁷Rb vapor and nitrogen buffer gas enclosed in a sealed glass cell, we have obtained the most accurate Rb diffusion coefficient in such an environment. This measurement also relied on spectroscopy of pressure broadened resonances to determine the buffer gas concentration. Examples of complementary studies in the frequency domain include the work in Ref. 14.



3. THEORETICAL BACKGROUND

Figure 1. Schematic of the coherence magnetometer.

Figure 1 shows a schematic of a "coherence" magnetometer. Here, a spatially modulated coherence grating is created between adjacent magnetic sublevels of the ground state in Rb vapor by an excitation pulse that consists of two perpendicular linear-polarized traveling waves, with wave vectors $\vec{k_1}$ and $\vec{k_2}$, aligned at a small angle θ (a few mrad). The grating is formed along the direction $\Delta \vec{k} = \vec{k_1} - \vec{k_2}$ as shown in Fig. 2 and has a spatial periodicity of $\sim \lambda/\theta$, where $\lambda = 2\pi/k$ and k is the magnitude of the wave vector $k = |\vec{k_1}| = |\vec{k_2}|$. The grating can be detected by applying a read-out pulse along the direction $\vec{k_2}$, and observing the coherent emission scattered along the phase-matched direction $\vec{k_1}$. This signal, called the magnetic grating free induction decay (MGFID)¹⁵ exhibits a Gaussian decay with a time constant $\tau = 2/ku\theta$, where u is the most probable speed associated with the Maxwell-Boltzmann velocity distribution. This decay corresponds to the thermal motion of atoms causing the grating to dephase. The scattered electric field from the grating is then given by

$$E(t) = E_0 e^{-\left(\frac{ku\theta}{2}\right)^2 t^2}$$
(1)

In the presence of a magnetic field, the functional form of the coherence can have a complicated dependence, parametrized by the Larmor frequency. This behavior has been described in Refs. 9 and 10, based on the formalism presented in Ref. 16. While Eq. 1 assumes the thermal trajectory of the atoms is uninterrupted over the length scale of the grating, in the presence of a high concentration of buffer gas the mean-free path of Rb atoms is reduced by collisions and may become much less than the grating spacing. In this limit, the motion of Rb atoms becomes a random walk that can be modeled by the diffusion equation¹³. This condition is represented by

$$\frac{\delta u}{\Gamma_{Col}} \ll \frac{1}{k\theta} \tag{2}$$



Figure 2: Upper figure shows directions of the excitation pulses, read--out pulse, and signal. The lower figure shows the relative timing of the pulse envelopes along $\vec{k_1}$ and $\vec{k_2}$ and the signal envelopes recorded on the detector.

Here, δu is the average velocity change per collision and is the effective collisional rate. When Eq. 2 is satisfied, the evolution of the ground-state density matrix ρ can be described by the diffusion equation,

$$\frac{\partial \rho(x,t)}{\partial t} = -D\nabla^2 \rho(x,t).$$
(3)

Here, *D* is the diffusion coefficient, which is inversely proportional to the perturber pressure. *D* can be accurately converted to its value at atmospheric pressure D_0 , using the relationship $D_0P_0 = DP$. Here, P_0 is atmospheric pressure and *P* is the buffer gas pressure in the experiment^{17,18}. If the x axis is along $\overline{\Delta k}$, the spatial dependence of the coherence ρ may be written as $e^{ik\theta x}$. This results in

$$\frac{\partial \rho(x,t)}{\partial t} = -(\theta k)^2 D \rho(x,t) \tag{4}$$

The solution to Eq. 4 is a decaying exponential with a time constant $(k\theta)^2 D$. The MGFID is therefore given by

$$E(t) = E_0 e^{-(\theta k)^2 D t}$$
⁽⁵⁾

Under these conditions, the coherent scattering from the grating is preserved but the signal exhibits an exponential decay with a characteristic time constant $\tau = 1/(D(k\theta)^2)$. Since $(k\theta)^{-1}$ represents the characteristic length scale in this problem, namely the grating spacing, the scaling law for τ is representative of a random walk. Therefore, the coherence magnetometer offers a direct approach for measuring diffusion rates. However, this method is prone to inaccuracies since the scattered signal has a small amplitude and is sensitive to magnetic field gradients.

As a result, we have exploited an interesting aspect of the lin-perp-lin excitation, namely that it simultaneously produces a density grating due to optical pumping. This grating has the same spatial period as the coherence grating. Accordingly, we are able to record decays with much improved signal-to-noise ratios and with greater accuracy due to the insensitivity of the density grating to magnetic fields and field gradients. It should be noted that the density gratings used in this work can be modeled without atomic recoil or matter-wave interference effects¹⁹. By recording the decay time as a function of angle, we rely on Eq. 5 to measure the diffusion coefficient with a statistical uncertainty of 1%.

4. RESULTS AND DISCUSSION

With reference to the experimental setup described in Fig. 1, we use an ALS described in Ref. 1 and waveguide amplifier system described in Ref. 2 to produce the excitation laser beams. The excitation pulses are amplitude modulated using acousto-optic modulators driven by delay generators with time bases slaved to a rubidium atomic clock. The signal detection is accomplished using a balanced heterodyne arrangement described in Ref. 3. The experiments were carried out in isotopically pure ⁸⁷Rb vapor in a sealed reference cell containing nitrogen buffer gas. The cell length was 10 cm and it was maintained at 50°C. The decay time, τ of the population grating, was measured as a function of θ to obtain *D*. As expected, τ was verified to scale as $1/\theta^2$, which is the definitive signature of diffusion. The pressure in the cell was independently determined by measuring the pressure broadened and shifted absorption spectrum as described in Ref. 3.

Table 1 summarizes representative values of the Rb-N₂ diffusion coefficient. The smallest uncertainty prior to this work was achieved by Ref. 20 (2.5%). The discrepancy between measurements utilizing different techniques emphasizes the necessity of a variety of methods, subject to different systematic effects, in arriving at a more reliable value of D_0 . Additionally, accurate measurements of the diffusion coefficient constrain theoretical models of many particle systems.

Reference	Technique	$D_0 \ (\mathrm{cm}^2/\mathrm{s})$	D_0 rescaled to $50^{\circ}C^{a}(cm^2/s)$
Wasghul et al. ²¹	Optical pumping relaxation	0.28 at 150°C	0.19
Zeng et al. ²²	Optical pumping relaxation	0.20 at 70°C	0.18
Ishikawa et al. ²⁰	Magnetic resonance echo	0.159 ± 0.004 at 60° C	0.152 ± 0.004
Franz et al. ²³	Optical pumping relaxation	0.16 at 32°C	0.18
Erickson ²⁴	Optical pumping relaxation	0.30 at 180°C	0.18
This work ³	Dephasing of density grating	0.1819 ± 0.0024 at 50°C	0.1819 ± 0.0024

Table 1: Representative measurements of the Rb-N₂ diffusion coefficient at atmospheric pressure D_0 . Uncertainties are provided where available.

^aRescaled using $D \propto T^{3/2}$ ^{17,18}

5. CONCLUSION

We have demonstrated a distinctive and accurate measurement of the diffusion coefficient of Rb in N₂ relevant to magnetometry. Ideally, the systematic effect due to the N₂ concentration should be measured at buffer gas concentrations of several atmospheres so that spectra can be fit to a smooth lineshape. Since the buffer gas pressure in our isotopically purified rubidium cell could not be changed, we fit the pressure-broadened spectrum to a function appropriate for our pressure range in which the hyperfine features are partially resolved. From Table 1, we note that our measurement disagrees with the previous most precise measurement obtained using spin echoes²⁰. Although the diffusion coefficients measured by modeling optical pumping curves²¹⁻²⁴ are in good agreement with our results, we note that these measurements do not report error bounds. However, our determination appears to settle large discrepancies in previously reported values using different techniques. We propose to extend this technique to obtain the most accurate determinations of diffusion coefficients involving buffer gases relevant to Rb vapor magnetometers and a comparative study of the advantages of CMs over traditional time domain magnetometers that rely on the evolution of populations²⁵. These measurements will be carried out in a non-magnetic glass manifold in which buffer gas concentrations can be varied and measured independently to corroborate spectroscopy.

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